

towards differentiable magnetohydrodynamics on exascale hardware



jf1uids



Features of jf1uids

- differentiable, GPU-ready fluid simulator written in JAX
- inherently divergence free approach to MHD (based on (Pang and Wu, 2024))
- novel (near-)energy-conserving scheme for self-gravity stable at discontinuities
- conservative geometric formulation for radially symmetric problems
- physics modules in development: stellar wind, cosmic rays, cooling, ...
- fully open source



there is not differentiable, GPU-ready MHD code yet



finite differencing

Why (automatic) differentiability?

-continuous adjoint method-

calculate gradients through the simulator, based on the differentiability of the building blocks provided by the numerical framework \rightarrow reverse-mode autodiff

- inverse modeling by optimization
- improved simulation-based inference (Zeghal et al., 2022; Holzschuh et Thuerey, 2024))
- corrector in the loop (Um et. al, 2021)

Case Study I: Recovering Physical Parameters





radial 1d stellar wind simulation

aim: retrieve stellar mass and terminal wind velocity from the simulation output

Case Study II: MHD with Corrector in the Loop



correction step after every timestep: fluid state = fluid state + dt corrector

Only if we train through the differentiable simulator, can the corrector account for the simulator-corrector interaction!





Interesting Numerics I: Divergence Free MHD

Idea: Split MHD equations into a coupled hydrodynamic and magnetic system.

$$\mathbf{U}^{n+1} = S_A^{\underline{\Delta t}} \circ S_B^{\underline{\Delta t}} \circ S_A^{\underline{\Delta t}} \mathbf{U}^n$$

$$\begin{array}{c} \text{magnetic} \\ \text{hydro} \end{array}$$

$$\begin{array}{c} \text{div curl ... = 0} \end{array}$$

finite difference magnetic update (self-consistently also evolves the gas velocity field (and energy)): Lorentz force $S_{B} \begin{cases} \rho \partial_{t} \mathbf{v} = -\mathbf{B} \times \text{curl } \mathbf{B}, \\ \partial_{t} \mathbf{B} = \text{curl}(\mathbf{v} \times \mathbf{B}), \end{cases}$

implicit System!, if it holds: div curl ... = 0 🔽

R = (**B**, **v**), implicit 2nd order scheme, fixed point iteration

$$\mathbf{R}^{n+1} = \mathbf{R}^n + \Delta t \Psi \left(\frac{\mathbf{R}^n + \mathbf{R}^{n+1}}{2} \right)$$

in practice only a few iterations

based on Pang and Wu, 2024

Interesting Numerics II: Improved Self-Gravity

Which flux is moving in the field, how to subtract energy?

- a) use the centered fluxes (e.g. in Pluto) problem: energy not conserved because the cell centered bulk fluxes are not the actual Riemann fluxes moved in the potential
- b) use the Riemann fluxes for the energy update (as used in ATHENA) – problem in the standard approach: both cells do half of the work irrespecive of their energy content, leading to negative pressures at discontinuities







Preliminary Scaling Results

on simpler test code tinyfluids (https://github.com/leo1200/tinyfluids)



Literature

- Pang and Wu, 2024: <u>https://arxiv.org/abs/2410.05173</u>
- Zeghal et al., 2022: <u>https://arxiv.org/abs/2207.05636</u>
- Holzschuh et Thuerey, 2024: <u>https://arxiv.org/abs/2410.22573</u>
- Um et. al, 2021: <u>https://arxiv.org/abs/2007.00016</u>

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